Graphs

Agenda –Graphs

- Graph basics and definitions
 - Vertices/nodes, edges, adjacency, incidence
 - Degree, in-degree, out-degree
 - Degree, in-degree, out-degree
 - Subgraphs, unions, isomorphism
 - Adjacency matrices
- Types of Graphs
 - Trees
 - Undirected graphs
 - Simple graphs, Multigraphs, Pseudographs
 - Digraphs, Directed multigraph
 - Bipartite
 - Complete graphs, cycles, wheels, cubes, complete bipartite

Uses of Graph Theory in CS

- Car navigation system
- Efficient database
- Build a bot to retrieve info off WWW
- Representing computational models Many other applications.
- This course we focus more on the properties of algorithmic of graphs

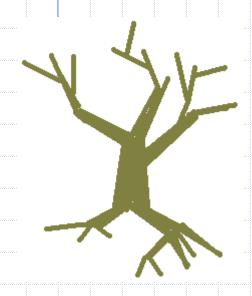
Graphs –Intuitive Notion

A graph is a bunch of vertices (or nodes) represented by circles • which are connected by edges, represented by line segments

Mathematically, graphs are binary-relations on their vertex set (except for multigraphs).

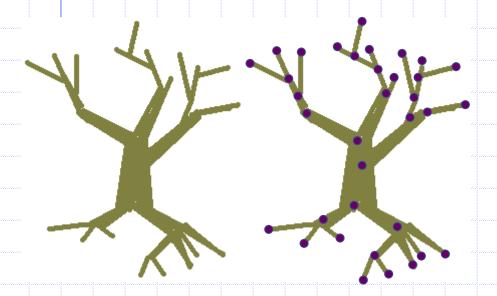
In Data Structures one often starts with trees and generalizes to graphs. In this course, opposite approach: We start with graphs and restrict to get trees.

A very important type of graph in CS is called a *tree*:



Real Tree

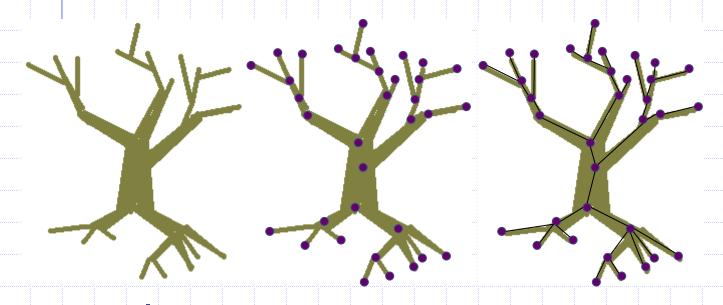
A very important type of graph in CS is called a *tree*:



Real Tree

transformation

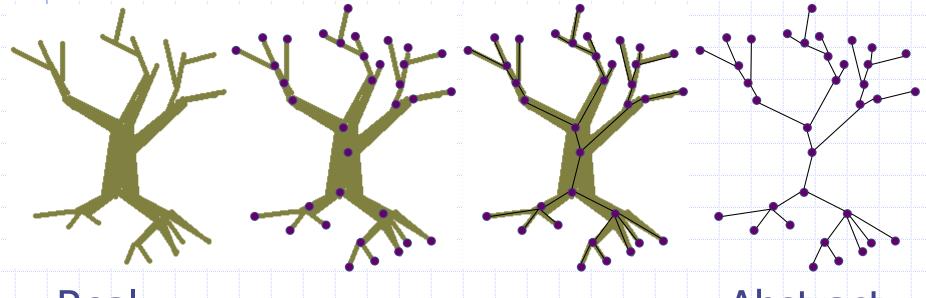
A very important type of graph in CS is called a *tree*:



Real Tree

transformation

A very important type of graph in CS is called a *tree*:



Real Tree

transformation

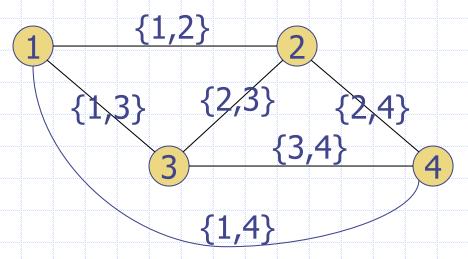
Abstract Tree

Different purposes require different types of graphs.

EG: Suppose a local computer network

- Is bidirectional (undirected)
- Has no loops (no "self-communication")
- Has unique connections between computers

Sensible to represent as follows:



- Vertices are labeled to associate with particular computers
- Each edge can be viewed as the set of its two endpoints

DEF: A **simple graph** G = (V, E) consists of a non-empty set V of **vertices** (or **nodes**) and a set E (possibly empty) of **edges** where each edge is a subset of V with cardinality 2 (an unordered pair).

Q: For a set 1/ with n elements, how many possible edges there?

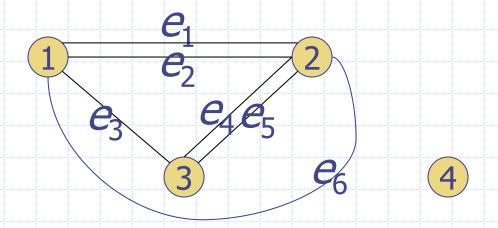
A: The number of pairs in *V*

$$= C(n,2) = n \cdot (n-1) / 2$$

Q: How many possible graphs are there for the same set of vertices *V*?

A: The number of subsets in the set of possible edges. There are $n \cdot (n-1) / 2$ possible edges, therefore the number of graphs on V is $2^{n(n-1)/2}$

If computers are connected via internet instead of directly, there may be several routes to choose from for each connection. Depending on traffic, one route could be better than another. Makes sense to allow multiple edges, but still no self-loops:



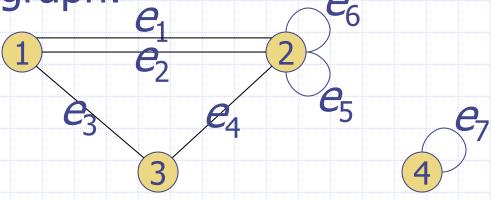
Edge-labels distinguish between edges sharing same endpoints. Labeling can be thought of as function:

$$e_1 \rightarrow \{1,2\}, e_2 \rightarrow \{1,2\}, e_3 \rightarrow \{1,3\}, e_4 \rightarrow \{2,3\}, e_5 \rightarrow \{2,3\}, e_6 \rightarrow \{1,2\}$$

DEF: A *multigraph* G = (V, E, f) consists of a non-empty set V of *vertices* (or *nodes*), a set E (possibly empty) of *edges* and a function f with domain E and codomain the set of pairs in V.

Pseudographs

If self-loops are allowed we get a pseudograph:



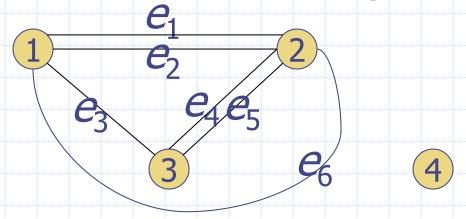
Now edges may be associated with a single vertex, when the edge is a loop

$$e_1 \rightarrow \{1,2\}, e_2 \rightarrow \{1,2\}, e_3 \rightarrow \{1,3\},$$

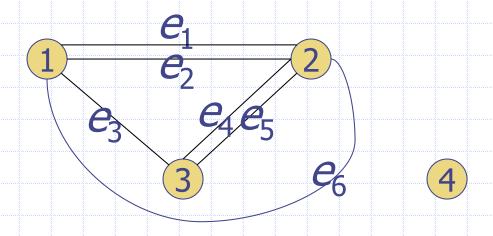
 $e_4 \rightarrow \{2,3\}, e_5 \rightarrow \{2\}, e_6 \rightarrow \{2\}, e_7 \rightarrow \{4\}_{17}$

DEF: A **pseudograph** G = (V, E, f) consists of a non-empty set V of **vertices** (or **nodes**), a set E (possibly empty) of **edges** and a function f with domain E and codomain the set of pairs and singletons in V.

Vertices are *adjacent* if they are the endpoints of the same edge.

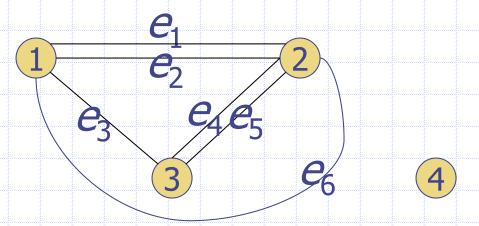


Q: Which vertices are adjacent to 1? How about adjacent to 2, 3, and 4?

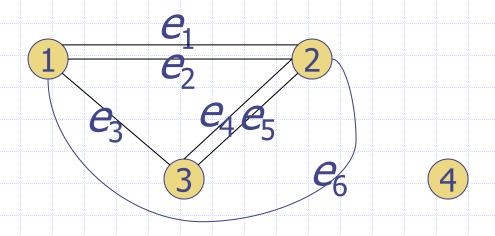


A: 1 is adjacent to 2 and 3
2 is adjacent to 1 and 3
3 is adjacent to 1 and 2
4 is not adjacent to any vertex

A vertex is *incident* with an edge (and the edge is incident with the vertex) if it is the endpoint of the edge.



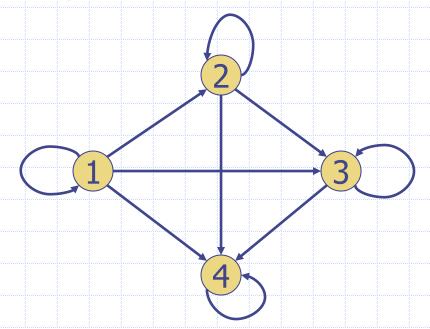
Q: Which edges are incident to 1? How about incident to 2, 3, and 4?



A: e_1 , e_2 , e_3 , e_6 are incident with 2

2 is incident with e_1 , e_2 , e_4 , e_5 , e_6 3 is incident with e_3 , e_4 , e_5 4 is not incident with any edge

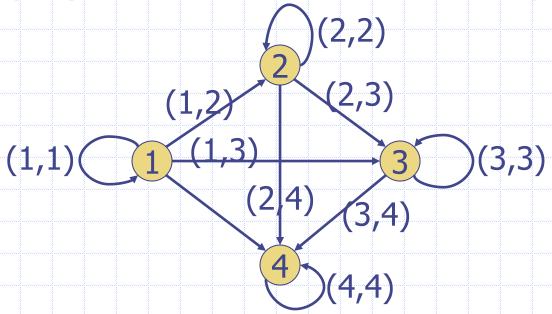
Last time introduced digraphs as a way of representing relations:



Q: What type of pair should each edge be (multiple edges not allowed)?

23

A: Each edge is directed so an *ordered* pair (or tuple) rather than unordered pair.



Thus the set of edges *E* is just the represented relation on *V*.

DEF: A directed graph (or digraph) G = (V, E) consists of a non-emptyset V of vertices (or nodes) and a set Eof edges with $E \subseteq V \times V$.

The edge (a,b) is also denoted by $a \rightarrow b$ and a is called the **source** of the edge while b is called the **target** of the edge.

Q: For a set 1/ with *n* elements, how many possible digraphs are there?

A: The same as the number of relations on V, which is the number of subsets of $V \times V$ so $2^{n \cdot n}$.

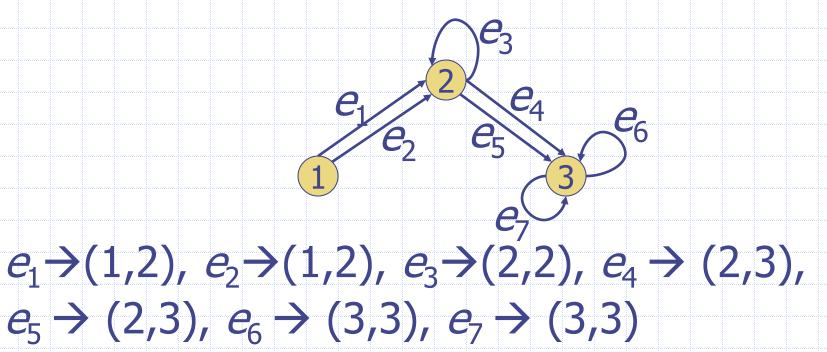
Directed Multigraphs

If also want to allow multiple edges in a digraph, get a *directed multigraph* (or *multi-digraph*).

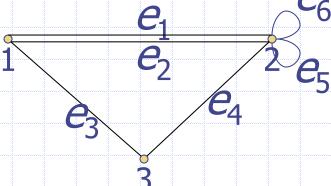
Q: How to use sets and functions to deal with multiple directed edges, loops?

Directed Multigraphs

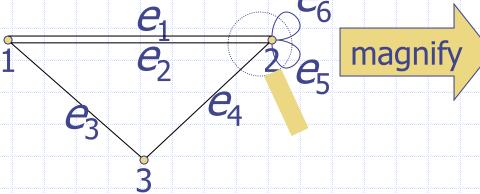
A: Have function with domain the edge set and codomain $V \times V$.



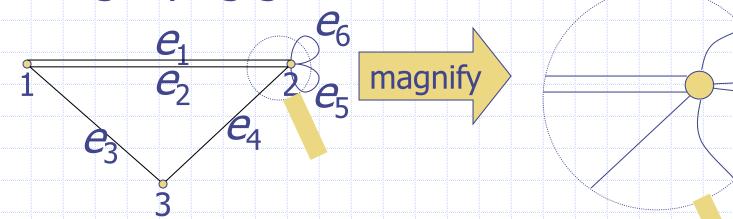
The *degree* of a vertex counts the number of edges that *seem* to be sticking out if you looked under a magnifying glass:



The *degree* of a vertex counts the number of edges that *seem* to be sticking out if you looked under a magnifying glass:



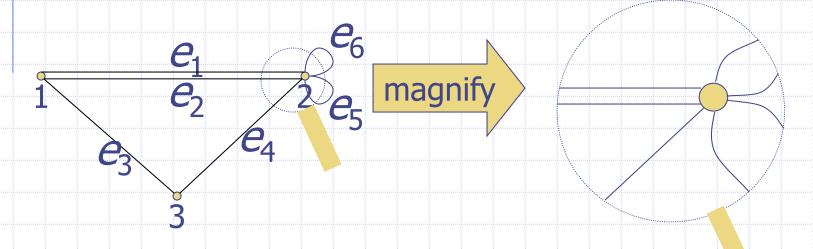
The *degree* of a vertex counts the number of edges that *seem* to be sticking out if you looked under a magnifying glass:



Thus deg(2) = 7 even though 2 only incident with 5 edges.

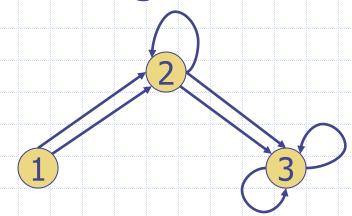
Q: How to define this formally?

A: Add 1 for every regular edge incident with vertex and 2 for every loop. Thus deg(2) = 1 + 1 + 1 + 2 + 2 = 7



Oriented Degree when Edges Directed

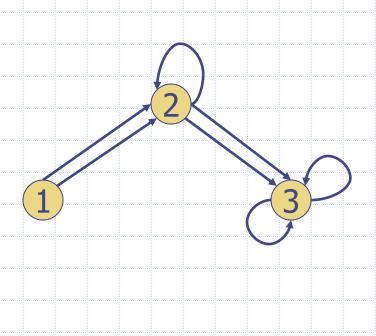
The *in-degree* of a vertex (deg⁻) counts the number of edges that stick *in* to the vertex. The *out-degree* (deg⁺) counts the number sticking *out*.



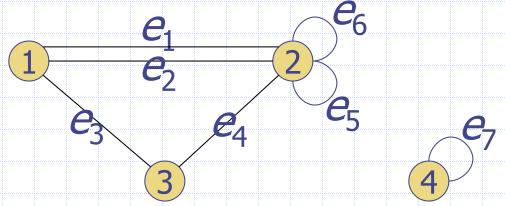
Q: What are in-degrees and out-degrees of all the vertices?

Oriented Degree when Edges Directed

A: deg(1) = 0 deg(2) = 3 deg(3) = 4 $deg^{+}(1) = 2$ $deg^{+}(2) = 3$ $deg^{+}(3) = 2$



Handshaking Theorem



There are two ways to count the number of edges in the above graph:

- 1. Just count the set of edges: 7
- Count seeming edges vertex by vertex and divide by 2 because double-counted edges: (deg(1)+deg(2)+deg(3)+deg(4))/2 = (3+7+2+2)/2 = 14/2 = 7

Handshaking Theorem

THM: In an undirected graph

$$|E| = \frac{1}{2} \sum_{e \in E} \deg(e)$$

In a directed graph

$$|E| = \sum_{e \in E} \operatorname{deg}^+(e) = \sum_{e \in E} \operatorname{deg}^-(e)$$

Q: In a party of 5 people can each person be friends with exactly three others?

Handshaking Theorem

A: Imagine a simple graph with 5 people as *vertices* and edges being undirected edges between friends (simple graph assuming friendship is symmetric and irreflexive). Number of friends each person has is the degree of the person.

Handshaking would imply that |E| = (sum of degrees)/2 or 2|E| = (sum of degrees) = (5.3) = 15. Impossible as 15 is not even. In general:

Handshaking Theorem

Lemma: The number of vertices of odd degree must be even in an undirected graph.

Proof: Otherwise would have

2|E| = Sum of even no.'s

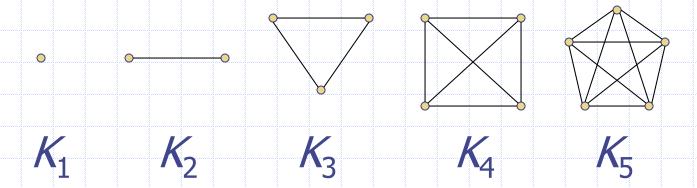
+ an odd number of odd no.'s

→even = even + odd

−this is impossible. □

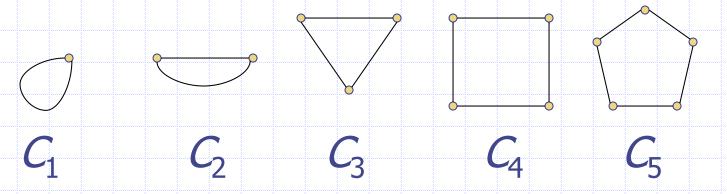
Graph Patterns Complete Graphs - K_n

A simple graph is **complete** if every pair of distinct vertices share an edge. The notation K_n denotes the complete graph on n vertices.



Graph Patterns Cycles - C_n

The *cycle graph* C_n is a circular graph with $V = \{0,1,2,...,n-1\}$ where vertex i is connected to i+1 **mod** n and to i-1 **mod** n. They look like polygons:

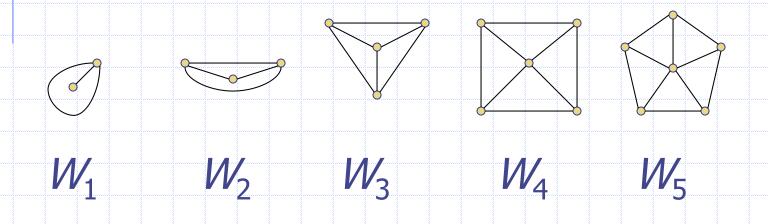


Q: What type of graph are C_1 and C_2 ?

Graph Patterns Wheels - W_n

A: Pseudographs

The **wheel graph** W_n is just a cycle graph with an extra vertex in the middle:



Usually consider wheels with 3 or more spokes only.

Graph Patterns Cubes - Q_n

The *n-cube* Q_n is defined recursively. Q_0 is just a vertex. Q_{n+1} is gotten by taking 2 copies of Q_n and joining each vertex ν of Q_n with its copy ν' :

 Q_3 Q_4 (hypercube)

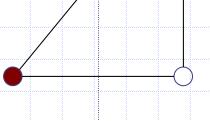
A simple graph is *bipartite* if V can be partitioned into $V = V_1 \cup V_2$ so that any two adjacent vertices are in different parts of the partition. Another way of expressing the same idea is bichromatic: vertices can be colored using two colors so that no two vertices of the same color are adjacent.

EG: C₄ is a bichromatic:

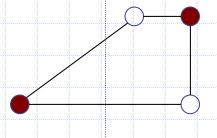
EG: C_4 is a bichromatic:

EG: C_4 is a bichromatic:

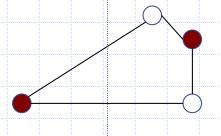
EG: C_4 is a bichromatic:



EG: C_4 is a bichromatic:



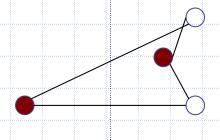
EG: C_4 is a bichromatic:



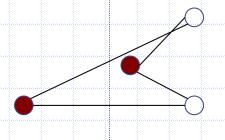
EG: C_4 is a bichromatic:



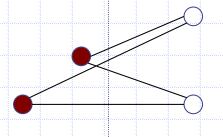
EG: C_4 is a bichromatic:



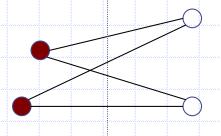
EG: C_4 is a bichromatic:



EG: C_4 is a bichromatic:

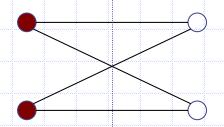


EG: C_4 is a bichromatic:



EG: C₄ is a bichromatic:

And so is bipartite, if we redraw it:



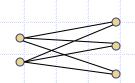
Q: For which n is C_n bipartite?

A: C_n is bipartite when n is even. For even n color all odd numbers red and all even numbers green so that vertices are only adjacent to opposite color.

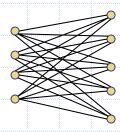
If n is odd, C_n is not bipartite. If it were, color 0 red. So 1 must be green, and 2 must be red. This way, all even numbers must be red, including vertex n-1. But n-1 connects to $0 \rightarrow \leftarrow$.

Graph Patterns Complete Bipartite - $K_{m,n}$

When all possible edges exist in a simple bipartite graph with m red vertices and n green vertices, the graph is called $complete\ bipartite$ and the notation $K_{m,n}$ is used. EG:



 $K_{2,3}$

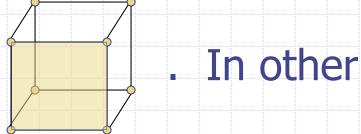


*K*_{4,5}

Subgraphs

Notice that the 2-cube occurs

inside the 3-cube



words, Q_2 is a subgraph of Q_3 :

DEF: Let G = (V, E) and H = (W, F) be graphs. H is said to be a **subgraph** of G, if $W \subseteq V$ and $F \subseteq E$.

Q: How many Q_2 subgraphs does Q_3 have?

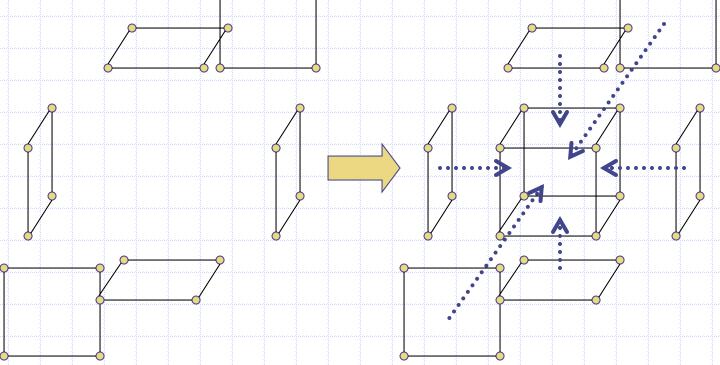
58

Subgraphs

A: Each face of Q_3 is a Q_2 subgraph so the answer is 6, as this is the number of faces on a 3-cube:

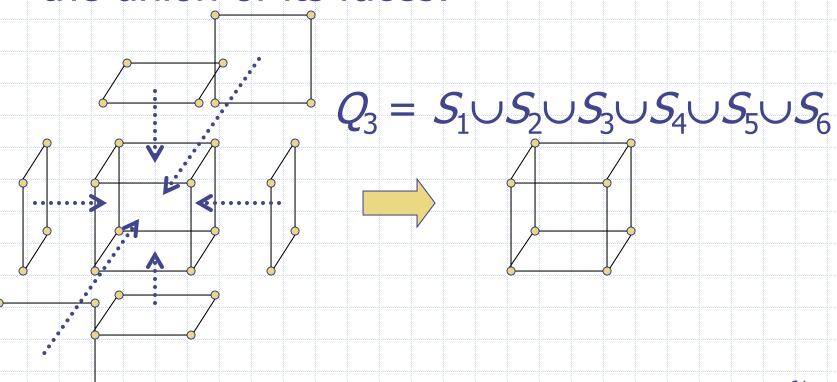
Unions

In previous example can actually reconstruct the 3-cube from its 6 2-cube faces:



Unions

If we assign the 2-cube faces (aka Squares) the names S_1 , S_2 , S_3 , S_4 , S_5 , S_6 then Q_3 is the union of its faces:



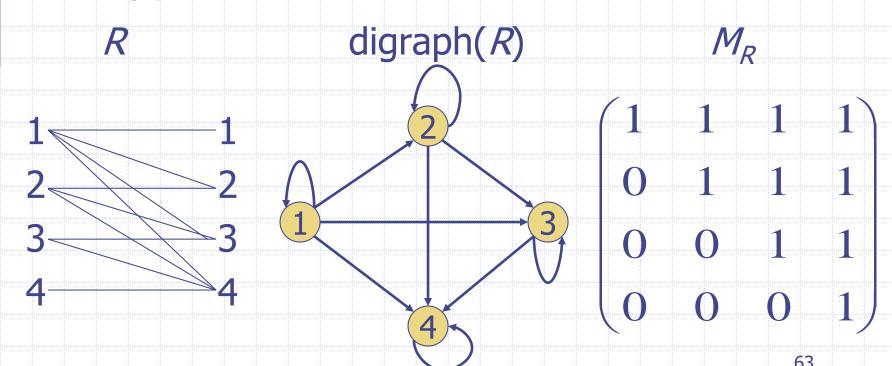
Unions

DEF: Let $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ be two simple graphs (and V_1, V_2 may or may not be disjoint). The **union** of G_1, G_2 is formed by taking the union of the vertices and edges. I.E: $G_1 \cup G_2 = (V_1 \cup V_2, E_1 \cup E_2)$.

A similar definitions can be created for unions of digraphs, multigraphs, pseudographs, etc.

Adjacency Matrix

We already saw a way of representing relations on a set with a Boolean matrix:



Adjacency Matrix

Since digraphs *are* relations on their vertex sets, can adopt the concept to represent digraphs. In the context of graphs, we call the representation an *adjacency matrix*:

For a digraph G = (V, E) define matrix A_G by:

- ◆ Rows, Columns –one for each vertex in
- ◆ Value at ith row and jth column is
 - 1 if i^{th} vertex connects to j^{th} vertex $(i \rightarrow j)$
 - 0 otherwise

Adjacency Matrix -Directed Multigraphs

Can easily generalize to directed multigraphs
by putting in the number of edges between
vertices, instead of only allowing 0 and 1:

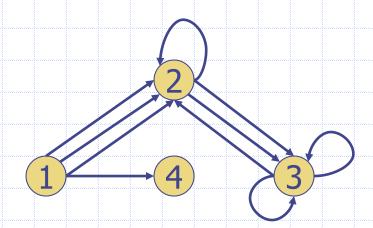
For a directed multigraph G = (1/F) define

For a directed multigraph G = (V, E) define the matrix A_G by:

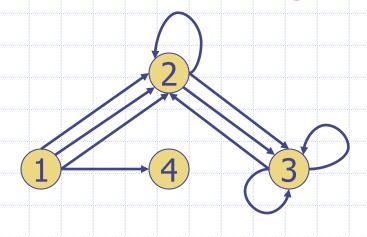
- ◆ Rows, Columns –one for each vertex in
- ◆ Value at ith row and jth column is
 - The number of edges with source the *i*th vertex and target the *j*th vertex

Adjacency Matrix -Directed Multigraphs

Q: What is the adjacency matrix?



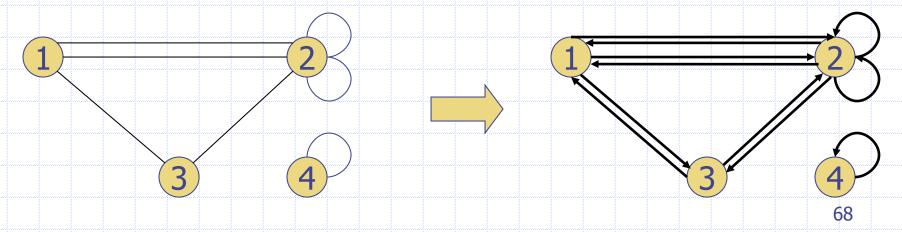
Adjacency Matrix -Directed Multigraphs



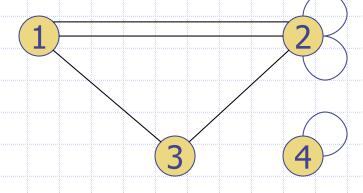
A:

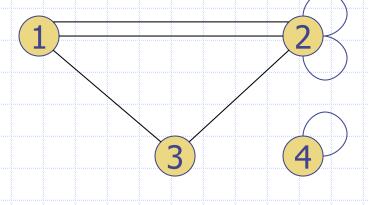
1		\mathbf{c}	$\mathbf{\Omega}$	1	
() (3	0	1	,
_		_			
()	1	2	0	
		4			
)	1	2	\mathbf{C}	
		\mathbf{a}			
) (U	U	C	

Undirected graphs can be viewed as directed graphs by turning each undirected edge into two oppositely oriented directed edges, except when the edge is a self-loop in which case only 1 directed edge is introduced. EG:



Q: What's the adjacency matrix?





A:

Notice that answer is *symmetric*.

For an undirected graph G = (V, E) define the matrix A_G by:

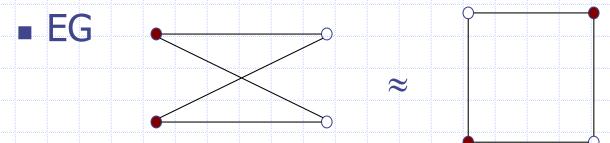
- ◆Rows, Columns –one for each element of
- ◆ Value at ith row and jth column is the number of edges incident with vertices i and j.

This is equivalent to converting first to a directed graph as above. Or by allowing undirected edges to take us from *i* to *j* can simply use definition for directed graphs.

Graph Isomorphism

Various mathematical notions come with their own concept of *equivalence*, as opposed to equality:

- Equivalence for sets is bijectivity:
 - EG $\{ \ \ \ \ \ \ \ \ \ \ \ \ \} \approx \{12, 23, 43\}$
- Equivalence for graphs is isomorphism:



Graph Isomorphism

Intuitively, two graphs are isomorphic if can bend, stretch and reposition vertices of the first graph, until the second graph is formed. Etymologically, *isomorphic* means "same shape".

EG: Can twist or relabel:

to obtain:

Graph Isomorphism Undirected Graphs

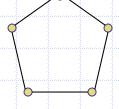
- DEF: Suppose $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are pseudographs. Let $f: V_1 \rightarrow V_2$ be a function s.t.:
- 1) f is bijective
- 2) for all vertices u, v in V_1 , the number of edges between u and v in G_1 is the same as the number of edges between f(u) and f(v) in G_2 .

Then f is called an **isomorphism** and G_1 is said to be **isomorphic** to G_2 .

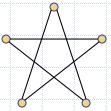
Graph Isomorphism Digraphs

- DEF: Suppose $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are directed multigraphs. Let $f: V_1 \rightarrow V_2$ be a function s.t.:
- 1) f is bijective
- 2) for all vertices u, v in V_1 , the number of edges from u to v in G_1 is the same as the number of edges between f(u) and f(v) in G_2 .
- Then f is called an isomorphism and G_1 is said to be isomorphic to G_2 .
- Note: Only difference between two definitions is the italicized "from" in no. 2 (was "between").

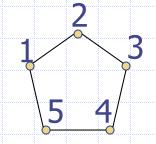
EG: Prove that

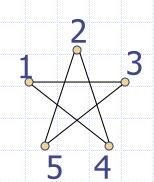


is isomorphic to

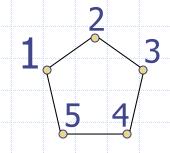


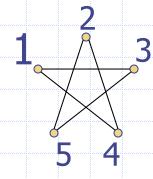
First label the vertices:



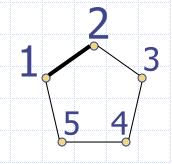


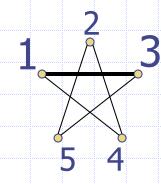
Next, set f(1) = 1 and try to walk around clockwise on the star.



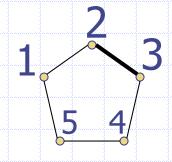


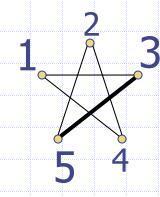
Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3.



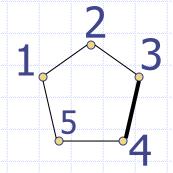


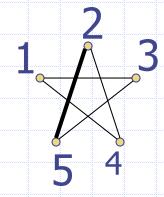
Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3. Next vertex is 5 so set f(3) = 5.



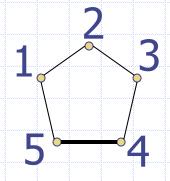


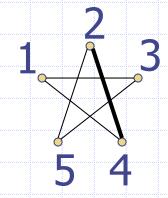
Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3. Next vertex is 5 so set f(3) = 5. In this fashion we get f(4)= 2



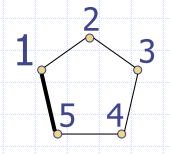


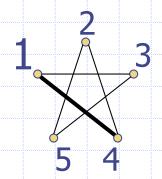
Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3. Next vertex is 5 so set f(3) = 5. In this fashion we get f(4)= 2, f(5) = 4.



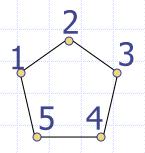


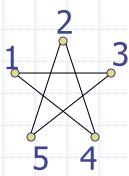
Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3. Next vertex is 5 so set f(3) = 5. In this fashion we get f(4) = 2, f(5) = 4. If we would continue, we would get back to f(1) = 1 so this process is well defined and f is a morphism.





Next, set f(1) = 1 and try to walk around clockwise on the star. The next vertex seen is 3, not 2 so set f(2) = 3. Next vertex is 5 so set f(3) = 5. In this fashion we get f(4) = 2, f(5) = 4. If we would continue, we would get back to f(1) = 1 so this process is well defined and f is a morphism. Finally since f is bijective, f is an isomorphism.





Properties of Isomorphims

Since graphs are completely defined by their vertex sets and the number of edges between each pair, isomorphic graphs must have the same intrinsic properties. I.e. isomorphic graphs have the same...

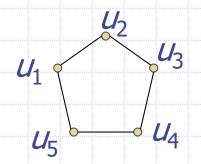
...number of vertices and edges

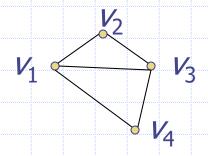
...degrees at corresponding vertices

...types of possible subgraphs

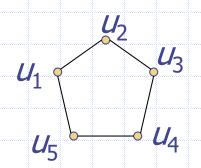
...any other property defined in terms of the basic graph theoretic building blocks!

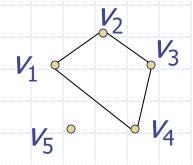
Once you see that graphs are isomorphic, easy to prove it. Proving the opposite, is usually more difficult. To show that two graphs are non-isomorphic need to show that no function can exist that satisfies defining properties of isomorphism. In practice, you try to find some intrinsic property that differs between the 2 graphs in question.



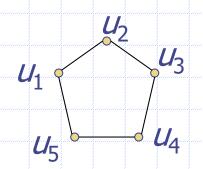


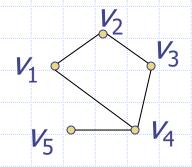
A: 1st graph has more vertices than 2nd.



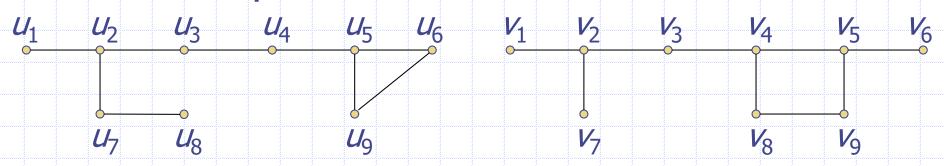


A: 1st graph has more edges than 2nd.

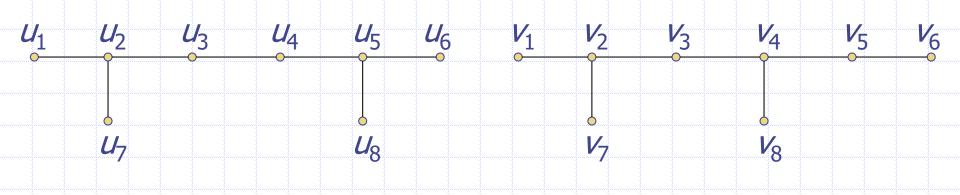




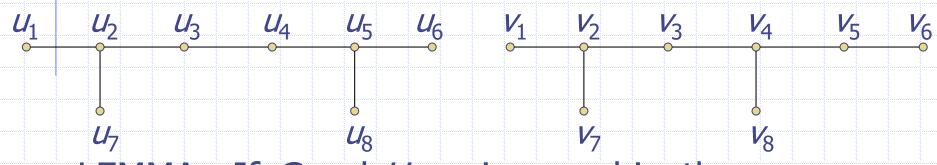
A: 2nd graph has vertex of degree 1, 1st graph doesn't.



A: 1st graph has 2 degree 1 vertices, 4 degree 2 vertex and 2 degree 3 vertices. 2nd graph has 3 degree 1 vertices, 3 degree 2 vertex and 3 degree 3 vertices.



A: None of the previous approaches work as there are the same no. of vertices, edges, and same no. of vertices per degree.



LEMMA: If *G* and *H* are isomorphic, then any subgraph of *G* will be isomorphic to some subgraph of *H*.

Q: Find a subgraph of 2nd graph which isn't a subgraph of 1st graph.

91

A: This subgraph is not a subgraph of the left graph.

 U_6

 u_7 u_8 v_7 v_8 Why not? Deg. 3 vertices must map to deg. 3 vertices. Since subgraph and left graph are symmetric, can assume v_7 maps to u_2 . Adjacent

deg. 1 vertices to v_2 must map to degree 1 vertices, forcing the deg. 2 adjacent vertex v_3 to map to u_3 . This forces the other vertex adjacent to v_3 , namely v_4 to map to u_4 . But then a deg. 3 vertex has mapped to a deg. 2 vertex $\rightarrow \leftarrow \square^{92}$

Blackboard Exercise

Show that W_6 is not bipartite.